

# Filling Graphics Primitives

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This note details a few points that the algorithm in the book that could help you in the implementation.

## 1 Polygon

I would change the ET-element and the AET-element data structures to contain the following information:

- $y_{\max}$ : maximal  $y$ -coordinate of the edge
- $x$ : current intersection
- $\delta$ : the integer part of  $(x_{\max} - x_{\min}) / (y_{\max} - y_{\min})$
- $\epsilon$ : the remainder part of  $(x_{\max} - x_{\min}) / (y_{\max} - y_{\min})$
- $dy = y_{\max} - y_{\min}$ : the difference between  $y_{\max}$  and  $y_{\min}$
- $cx$ : the current, accumulated remainder

For example, instead of the ET-element  $[3, 7, \frac{-5}{2}, next]$ , I would store the following element  $[3, 7, -2, -1, 2, 0, next]$  where  $next$  is the pointer to the next element.

Another example is that the ET-element  $[5, 7, \frac{6}{4}, next]$  will be stored as  $[5, 7, 1, 2, 4, 0, next]$ .

### 1.1 Initializing in ET

When we add an edge specified by the two points  $(x_{\min}, y_{\min})$  and  $(x_{\max}, y_{\max})$  to the AET, what are the values of  $\delta$  and  $\epsilon$ ? These two values can be computed as follows:

- $\delta = (x_{\max} - x_{\min}) / (y_{\max} - y_{\min})$
- $\epsilon = (x_{\max} - x_{\min}) \% (y_{\max} - y_{\min})$

The integer arithmetic of JAVA can be used to determine  $\delta$  and  $\epsilon$ .

## 1.2 Update in AET

Given this data structure, I will compute the next intersection using the following algorithm.

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### Algorithm 1 procedure update(e: AET-element)

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1: // update current  $x$ 
2:  $e.x := e.x + e.\delta$ 
3: // update remainder  $cx$ 
4:  $e.cx := e.cx + e.\epsilon$ 
5: // process  $cx$ 
6: if  $|e.cx| \geq |e.dy|$  then
7:    $e.x := e.x + e.cx/e.dy$ 
8:    $e.cx := e.cx \% e.dy$ 
9: end if

```

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## 1.3 Remark

Implicitly, Algorithm 1 does some rounding up in the coordinate of the intersection. In using the value to decide which pixels should be set, the following situations need to be considered:

1. Rounding up when  $cx > 0$  —  $x$  should be increased by 1
2. Rounding up when  $cx < 0$  — nothing needs to be done (already rounded up)
3. Rounding down when  $cx > 0$  — nothing needs to be done (already rounded down)
4. Rounding down when  $cx < 0$  —  $x$  should be decreased by 1

## 1.4 Example

The next tables demonstrate the update algorithm for two edges:  $AB$  and  $BC$  from Figure 3.22 from the book.

Edge	AB	3	7	-2	-1	2	0
Step in Alg.	Scan line	$y_{\max}$	$x$	$\delta$	$\epsilon$	$dy$	$cx$
	1	3	7	-2	-1	2	0
	2	3	5	-2	-1	2	-1
after line 4	3	3	3	-2	-1	2	-2
final	3	3	2	-2	-1	2	0

Computation for the edge  $AB$

Edge	BC	5	7	1	2	4	0
Step in Alg.	Scan line	$y_{\max}$	$x$	$\delta$	$\epsilon$	$dy$	$cx$
	1	5	7	1	2	4	0
	2	5	8	1	2	4	2
after line 4	3	5	9	1	2	4	4
final	3	5	10	1	2	4	0
	4	5	11	1	2	4	2
after line 4	5	5	12	1	2	4	4
final	5	5	13	1	2	4	0

Computation for the edge  $BC$