# The Egg Cracking Problem

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# Talk Overview

- Introduction
- The Egg Cracking Problem
  - A formalization
- Conclusion

# Introduction

- What's AI?
- Commonsense reasoning
- Question answering
- The Common Sense problem page:

http://www-formal.stanford.edu/leora/cs

Commonsense Reasoning	
• Reasoning we do in our everyday lives. Grapes are fruit. Bananas are fruit. Onions are neither grapes nor bananas.	
• What if we later learned the following information? Onions are herbs.	
<ul> <li>Reasoning with incomplete information and the ability tretract previously drawn conclusions (non-monotonic reasoning).</li> </ul>	ο

# **Question Answering**

•  $\Phi \vdash \alpha$ 

 $\Phi$  is a set of first-order formulae, or knowledge base, and  $\alpha$  is a first-order formula, the question.

### • Theorem resolution

# Formalization Evaluation Criteria [1]

- Epistemological adequacy
- Faithfulness to the real world
- Reusability
- Elaboration tolerance

# The Egg Cracking Problem

### Description

A cook is cracking a raw egg against a glass bowl. Properly performed, the impact of the egg against the edge of the bowl will crack the eggshell in half. Holding the egg over the bowl, the cook will then separate the two halves of the shell with his fingers, enlarging the crack, and the contents of the egg will fall gently into the bowl. The end result is that the entire contents of the egg will be in the bowl, with the yolk unbroken, and that the two halves of the shell are held in the cook's fingers.

### Questions

What happens if: The cook brings the egg to impact very quickly? Very slowly? The cook lays the egg in the bowl and exerts steady pressure with his hand? The cook, having cracked the egg, attempts to peel it off its contents like a hard-boiled egg? The bowl is made of loose leaf paper? of soft clay? The bowl is smaller than the egg? The bowl is upside down? The cook tries this procedure with a hardboiled egg? With a coconut? With an M & M?

### Credits

Contributed by Ernest Davis (davise@cs.nyu.edu), New York University, U.S.A. (18th September 1997)

A Formalization
<ul> <li>There is a physically feasible single-agent plan for the egg cracking problem [1].</li> </ul>
<ul> <li>Single agent plans can be defined inductively as follows:</li> </ul>
<ol> <li>if act is an action, then act is a plan;</li> <li>if plan1 and plan2 are plans, then seq(plan1, plan2) is a plan;</li> <li>if c is a sentence of our language, and plan1 and plan2 are plans, then cond(c, plan1, plan2) is a plan.</li> </ol>
<ul> <li>The physical feasibility of plan sequences is given by the following axiom:</li> </ul>
$(physfeas(plan1, start(i)) \land (occurs(plan1, i) \Rightarrow physfeas(plan2, end(i)))) \Rightarrow (1)$ $physfeas(seq(plan1, plan2), start(i))$
For condition sequences, if c is true, then plan1 is physically feasible. Otherwise, plan2 is physically feasible.

### Assumptions

bowl(b)	(2)
upright(b, s)	(3)
empty(b, s)	(4)
hard(b)	(5)
WholeEgg(x, s)	(6)
raw(x, s)	(7)
above(loc, b, s)	(8)
$capacity(b) \ge vol(x)$	(9)

### Goal (feasibility)

First we hit the egg against the bowl causing a crack. Then we quickly move the egg over the bowl. Next if the crack is facing up, we turn the crack so that it's facing down. Lastly, we open the shell of the egg.

Physfeas(seq(a1, a2, a3, a4), s)	(10)
where	
a1 = hit-against(eggshell(x), b, cf(eggshell(x), b))	(11)
a2 = qmove(x, loc)	(12)
$a3 = cond(\neg down(gap(x, now)), qflip(x))$	(13)
a4 = openshell(x, down)	(14)

### Goal (occurs)

First we hit the egg against the bowl causing a crack. Then we quickly move the egg over the bowl. Next if the crack is facing up, we turn the crack so that it's facing down. Lastly, we open the shell of the egg. If we can do all of this, then contents of the egg are still enclosed in the egg, which has a gap in it's shell, and the yolk is not broken.

$occurs(seq(a1, a2, a3, a4), i) \Rightarrow (c1 \land c2 \land c3)$	(15)
where	
a1 = hit - against(eggshellof(x), b, cf(eggshellof(x), b))	(16)
a2 = qmove(x, loc)	(17)
$a3 = cond(\neg down(gap(x, now)), qflip(x))$	(18)
a4 = openshell(x, down)	(19)
and	
c1 = enc - gs(yolkof(x), x, end(i))	(20)
c2 = enc-gs(eggwhiteof(x), x, end(i))	(21)
$c3 = \neg broken(yolkof(x), end(i))$	(22)

### Goal (opening the egg)

 $(c1 \land c2 \land c3 \land c4 \land c5 \land c6) \Rightarrow (r1 \land r2)$ 

If the egg is cracked, it's contents are still intact, the egg is above the bowl, the bowl is large enough to hold the contents of the egg, and we open the egg, then the contents of the egg will fall into the bowl.

where	
c1 = CrackedEgg(x, start(i))	(24)
c2 = occurs(openshell(eggshellof(x), down), i)	(25)
c3 = enc - gs(yolkof(x), start(i))	(26)
c4 = enc-gs(eggwhiteof(x), start(i))	(27)
$c5 = above(x, o, i) \land bowl(o) \land upright(o) \land empty(o, start(i))$	(28)
$c6 = capacity(o) \ge vol(x)$	(29)
and	
r1 = enc - gs(yolkof(x), o, end(i))	(30)

r2 = enc - gs(eggwhiteof(x), o, end(i))	(31)

(23)

Α	A Formalization (Cont.)		
•	Salient properties of an egg:		
	<b>A:</b> An egg has four states. $egg(x) \Leftrightarrow NotYetLaid(x, s) \lor WholeEgg(x, s) \lor CrackEgg(x, s) \lor BrokenEgg(x, s)$	(32)	
	<b>A:</b> <i>if the egg is whole or cracked, then the egg holds together</i> $WholeEgg(x) \lor CrackedEgg(x, s) \Rightarrow together(x)$	(33)	
	<b>A:</b> An egg is a package consisting of a egg yolk and egg white as long as the egg is whole or cracked.		
	$(WholeEgg(x, i) \lor CrackedEgg(x, i)) \Rightarrow package(egginsideof(x), c, i)$	(34)	
	$c = \{eggyolk(x), eggwhite(x)\}.$		

A Formalization (Cont.)	
• The geometry an egg:	
<b>A:</b> The eggshell of a whole egg is a shell. WholeEgg(x, i) $\land$ eggshell(y, x) $\Rightarrow$ shell(shape(y, i))	(35)
<b>A:</b> The inside of the egg is the inside of a shell. WholeEgg(x, i) $\land$ egginsideof(y, x) $\Rightarrow$ ShellInside(shape(y, i), shape(x, i))	(36)
<b>T (35, 36, &amp; Def.)</b> : A whole egg is a filled shell. WholeEgg( $x, i$ ) $\Rightarrow$ FilledShell(shape( $x, i$ ))	(37)
<b>A:</b> An object inside of another object is said to be enclosed by that object and vice-versa.	
$inside(shape(y, i), shape(x, i)) \Leftrightarrow enclosed(y, x, i)$	(38)
<b>T (37 &amp; Def.):</b> If an object is inside of a shell, then that object is enclosed by the shell.	
$shell(shape(x, i)) \land ShellInside(shape(y, i), shape(x, i)) \Rightarrow enclosed(y, x, i)$	(39)
<b>T (35, 36, &amp; 39):</b> The egg shell of a whole egg enclose the inside of an egg.	
$Whole Egg(x, i) \land eggshell(z, x) \land egginside(y, x) \Rightarrow enclosed(y, z, i)$	(40)

A Formalization (Cont.)	
<ul> <li>Material of an egg:</li> </ul>	
A: Eggshells are breakable.	
$eggshell(y, x) \Rightarrow breakable(y)$	(41)
<b>A:</b> If an object is breakable and you hit it against something hard, then the object will crack.	
$breakable(x) \land hard(o) \land occurs(hitagainst(x, o, cf(x, o)), x) \Rightarrow cracked(x, end(i))$	(42)
A: If the egg is cracked, then the egg is a cracked-egg.	
$(egg(x) \land eggshell(x) \land cracked(y, i)) \Rightarrow CrackedEgg(x, i)$	(43)
<b>T (41, 42, &amp; 43):</b> If you hit the egg against something that's hard with enough force, it will crack.	
$(a1 \land a2 \land a3) \Rightarrow CrackedEgg(x, end(i))$	(44)
Where	
a1 = WholeEgg(x, start(i))	(45)
a2 = hard(o)	(46)
a3 = occurs(hitagainst(eggshellof(x), o, cf(eggshellof(x), i)), i)	
A: The raw egg white of is a liquid of high viscosity.	
$(egg(x) \land eggwhite(w, x) \land raw(w, s)) \Rightarrow (liquid(w, s) \land (viscosity(w, s) = high))$	(47)
A: Semisolid is solid.	
$semisold(x, s) \Rightarrow solid(x, s)$	(48)

A Formalization (Cont.)	
<ul> <li>Material of an egg (cont.):</li> </ul>	
<b>A</b> : A yolk is not very narrow. $(egg(x) \land yolk(y, x) \land narrow(z)) \Rightarrow larger(y, z)$	(49)
<b>A:</b> The yolk of a whole egg is never broken. WholeEgg( $x, s$ ) $\Rightarrow \neg$ BrokenYolk(yolkof( $x$ ), $s$ )	(50)

A: The yolk and white of a raw egg are raw.	
$(egg(x) \land raw(x, s) \land yolk(y, x) \land eggwhite(w, x)) \Rightarrow (raw(y, s) \land raw(w, s))$	(51)

# A Formalization (Cont.) The initial crack: A: If a shell has a gap and a shell inside of it, then the gapped shell enclose another shell. $Shellgap(r1, r2) \land (shape(x, i) = r1) \land shell - inside(shape(y, i), r1) \Rightarrow$ (52) enc - gs(y, x, i)A: If a gapped shell encloses a package, then it does so to the contents of the package and vice-versa. $package(y, S, i) \Rightarrow enc - gs(y, x, i) \Leftrightarrow \forall s \in S enc - gs(s, x, i)$ (53)A: If a gapped shell is facing up and encloses another object, then it encloses that object as long as it's facing up. (54) $(GappedShell(shape(x, i)) \land up(gap(x, i), i) \land enc - gs(y, x, start(i))) \Rightarrow$ enc - gs(y, x, end(i))

A Formalization (Cont.)	
The initial crack (cont.):	
<b>A:</b> If the object is solid and smaller than the gap, it will fall through the gap;	
If the object is solid and larger than the gap, it will stay enclosed by the gapped shell;	
if the object is a liquid with high viscosity, the gap is narrow, and the time duration of the gap facing down is short, then the object will stay inside the gapped shell;	
If the viscosity is low in the previous then the object will fall through the gap.	
$a1 \Longrightarrow c1 \land c2 \land c3 \land c4$	(55)
where	
$a1 = GappedShell(shape(x), i) \land down(gap(x), i) \land enc - gs(o, x, start(i))$	(56)
and	
$c1 = (solid(o) \land larger(o, gap(x, i))) \Rightarrow enc - gs(o, x, end(i))$	(57)
$c2 = (solid(o) \land smaller(o, gap(x, i)) \land (duration(i) = long)) \Rightarrow \\ fall - through(o, gap(x, i), i)$	(58)
$c3 = (liquid(o) \land (viscosity(o) = high) \land (duration(i) = short) \land narrow(gap(x, i))$ enc - gs(o, x, end	$ \Rightarrow (59) (i)) $
$\begin{aligned} (liquid(o) \land (viscosity(o) = low) \land (duration(i) = long)) \Rightarrow \\ fall - through(o, gap(x, i), i) \end{aligned}$	(60)

• The initial crack (cont.):

 $a1 \Longrightarrow (\forall o \in S).(c1 \land c2 \land c3 \land c4)$ 

### where

$$a1 = GappedShell(shape(x), i) \land down(gap(x), i) \land enc - gs(y, x, start(i)) \land package(y, S, start(i))$$

$$(62)$$

### and

$$c1 = (solid(o) \land larger(o, gap(x, i))) \Rightarrow enc - gs(o, x, end(i))$$
(63)

$$c2 = (solid(o) \land smaller(o, gap(x, i)) \land (duration(i) = long)) \Rightarrow$$

$$fall - through(o, gap(x, i), i)$$
(64)

$$c3 = (liquid(o) \land (viscosity(o) = high) \land (duration(i) = short) \land narrow(gap(x, i)) \Rightarrow (65)$$
$$enc - gs(o, x, end(i))$$

$$(liquid(o) \land (viscosity(o) = low) \land (duration(i) = long)) \Rightarrow$$

$$fall - through(o, gap(x, i), i)$$

$$(66)$$

(61)

AFC	ormalization (Cont.)	
•		
• Th	e initial crack (cont.):	
	<b>A:</b> A cracked egg is a narrow gapped shell. $CrackedEgg(x, i) \Rightarrow$ $(GappedShell(shape(eggshellof(x), i)) \land narrow(gap(eggshellof(x), i)))$	(67)
	<b>A:</b> During it's life a gapped shell will face only up or down throughout that time.	
	$Gappedshell(shape(x, i)) \Rightarrow \exists (i_1,, i_n).(c1 \land c2)$	(68)
	where	
	$c1 = ([i_1,, i_n] = i)$	(69)
	$c2 = (\forall i' \in \{i_1,, i_n\}(up(gap(x, i'), i')) \lor down(gap(x, i'), i'))$	(70)
	<b>T (54, 67, &amp; 68):</b> If moved quickly a cracked egg can be moved without the contents leaking out.	
	$(a1 \land a2 \land a3 \land a4 \land a5) \Rightarrow enc - gs(x, egginside of(x), end(i))$	(71)
	where	
	a1 = CrackedEgg(x, start(i))	(72)
	a2 = raw(x, i)	(73)
	a3 = enc - gs(x, egginside of(x), start(i))	(74)
	a4 = occurs(move(x, loc), i)	(75)
	a5 = (duration(i) = short)	(76)

Α	Formalization (Cont.)	
•	Opening up the egg:	
	A: If a gapped shell is open and it's above something, then it will fall onto that something. ( $occurs(openshell(x, down), i) \land above(x, o, i) \land enc - gs(y, x, start(i))) \Rightarrow$ occurs(fall - onto(y, o, i)))	(77)
	<b>A:</b> If an object falls onto a flat surface during some interval, it is on that surface at the end of that interval. On the other hand, if the object falls into a gapped shell (bowl) whose gap is up and which is not overly full, then the object will be enclosed by the gapped shell.	
	$occurs(fall - onto(x, o, i)) \Rightarrow (c1 \land c2)$	(78)
	where	
	$c1 = (flat - surface(shape(o, i)) \Rightarrow on(x, i, end(i)))$ $c2 = (a1 \land a2 \land a3 \land a4) \Rightarrow enc - gs(y, o, end(i))$ $a1 = Gappedshell(shape(o, i), i)$ $a2 = up(gap(o, i), i)$ $a3 = smaller(y, gap(o, i), i)$ $a4 = (capacity(o, start(i)) \ge (contents(o, start(i)) + vol(x)))$	(79) (80)
	<b>A:</b> A bowl is a gapped shell. $bowl(o) \Rightarrow GappedShell(shape(o, s))$	(81)
	<b>A</b> : A an upright bowl has it's gap facing up. $bowl(o) \land upright(o, s) \Rightarrow up(gap(o, s), s)$	(82)

<ul> <li>Opening up the egg (cont.):</li> </ul>
<b>A:</b> Empty bowls have nothing in them. $bowl(o) \land empty(o, s) \Rightarrow contents(o, s) = \emptyset$ (83)
<b>A:</b> If a package falls onto something, then the contents of that package fall onto that thing.
$(package(y, S, i) \land occurs(fall - onto(y, o), i)) \Rightarrow \forall x \in S(occurs(fall - onto(y, o), i)) (84)$
<b>T (34, 55, 78, 81, 83, &amp; 84):</b> If one opens up a cracked egg shell while the egg is over an upright bowl and the crack is turned down, and the bowl is empty, then the egg yolk and egg white are enclosed by the bowl.
$a1 \wedge a2 \wedge a3 \wedge a4 \wedge a5 \wedge a6 \Longrightarrow c1 \wedge c2 \tag{85}$
where
a1 = CrackedEgg(x, start(i))  (86)
a2 = occurs(openshell(eggshellof(x), down), i)  (87)
a3 = enc - gs(yolkof(x), start(i))  (88)
a4 = enc - gs(eggwhiteof(x), start(i))  (89)
$a5 = above(x, o, i) \land bowl(o) \land upright(o) \land empty(o, start(i)) $ (90)
and
c1 = enc - gs(yolkof(x), o, end(i))  (91)
c2 = enc - gs(eggwhiteof(x), o, end(i))  (92)

### • Opening up the egg (proof 85: 34, 55, 78, 81, 83, & 84):

**A34:** An egg is a package consisting of a egg yolk and egg white as long as the egg is whole or cracked.

**A55:** If the object is solid and smaller than the gap, it will fall through the gap.

If the object is solid and larger than the gap, it will stay enclosed by the gapped shell.

*if the object is a liquid with high viscosity, the gap is narrow, and the time duration of the gap facing down is short, then the object will stay inside the gapped shell.* 

If the viscosity is low in the previous, then the object will fall through the gap.

**A78:** If an object falls onto a flat surface during some interval, it is on that surface at the end of that interval. On the other hand, if the object falls into a gapped shell (bowl) whose gap is up (an upright bowl) and which is not overly full, then the object will be enclosed by the gapped shell.

A81: A bowl is a gapped shell.

**A83:** Empty bowls have nothing in them.

**A84:** If a package falls onto something, then the contents of that package fall onto that thing.

A Formalization (Cont.)	
<ul> <li>Feasibility of individual actions:</li> </ul>	
<b>A:</b> A null action is feasible. Physfeas(null, s)	(93)
<b>A:</b> To hit an object with a given force is feasible. Physfeas(hit – $against(x, o, f), s$ )	(94)
A: It is feasible that one can move an object if it is located in one place. $together(x, s) \Rightarrow Physfeas(move(x, loc), s)$	
<b>Def:</b> A quick move is a move which has a short duration. $Occurs(qmove(x, loc), i) \Leftrightarrow (Occurs(move(x, loc), i) \land (duration(i) = short))$	(95)
<b>T:</b> It is feasible to move a cracked egg. $CrackedEgg(x, s) \Rightarrow physfeas(qmove(x, loc), s)$	(96)
<b>A:</b> If an object is together, then it is feasible to flip it. $together(x, s) \Leftrightarrow Physfeas(flip(x), s)$	(97)

A Formalization (Cont.)	
Feasibility of individual actions (cont.):	
<b>Def.:</b> Flipping an object quickly is flipping an object within a short duration.	
$Occurs(qflip(x), i) \Leftrightarrow Occurs(flip(x), i) \land (duration(i) = short)$	(98)
<b>T:</b> It is feasible to flip a cracked egg. $CrackedEgg(x, s) \Rightarrow Physfeas(qflip(x), s)$	(99)
A: It is feasible to open up the shell of a raw cracked egg.	
$(a1 \land a2 \land a3) \Rightarrow Physfeas(openshell(x, down), s)$	(100)
Where	
a1 = CrackedEgg(x, s) a2 = raw(x, s)	(101) (102)
a3 = down(gap(eggshellof(x, s)), s)	(103)

A Formalization (Cont.)	
<ul> <li>Miscellaneous axioms on actions:</li> </ul>	
<b>A:</b> If an object is moved during an interval, then it's at the desired location at the end of the interval.	
$Occurs(move(x, loc, i)) \Rightarrow at(x, loc, end(i))$	(104)
<b>A:</b> If two objects are at a location and one of them is above the location, then it is also above the other object.	
$(at(x, loc, s) \land above(loc, o, s)) \Rightarrow above(x, o, s)$	(105)
<b>A:</b> If a gapped shell is facing up, then flipping it makes it face downward.	
$(a1 \land a2 \land a3) \Rightarrow down(gap(o, i), end(i))$	
where	
a1 = Gappedshell(shape(o, start(i)))	(106)
a2 = up(gap(o, i), start(i))	(107)
a3 = occurs(flip(o), i)	(108)

Frame axioms describe how the world stays the same [3].

### Example

 $\forall (a, x, s).((Holding(x, s) \land \neg (a = Release)) \Rightarrow Holding(x, Result(a, s)))$ (109)

Conclusion
<ul> <li>These formalizations seems to be an end result.</li> </ul>
<ul> <li>One characterization of reasoning is that we either reason based upon stored knowledge (experiences, memories, etc.) or that we reason without the use of stored knowledge [4,5].</li> </ul>
<ul> <li>Are there situations where we use both forms of reasoning? What about structural alignment?</li> </ul>

# Conclusion (cont.)• Consider the following axiom schema: $A(\Phi) \land \forall x'(\Phi(x') \Rightarrow P(x')) \Rightarrow \forall x'(P(x') \Rightarrow \Phi(x'))$ (110)A is a finite set of first-order formulae (i.e., a theory).P(x') is a predicate appearing in A. $A(\Phi)$ is the result of replacing all occurrences of P(x')) in A with $\Phi$ .• Without examples it is difficult to apply.

## References

- [1] Morgenstern, L., Foundation of a Logic of Knowledge, Action, and Communication, *Ph.D. thesis*, NYU, 1988.
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