

Nonmonotonic Inductive Logic Programming (NMILP)

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Outlines

- Why NMILP?
- SLDNF Based Approaches
- Moving from ILP to NMILP
- Stable Models Based Approaches

Why NMILP?

Nonmonotonic Logic Programming (NMLP)

- normal logic programs (CAW by NAF)
 $A_0 \leftarrow A_1, \dots, A_m, \text{not}A_{m+1}, \dots, \text{not}A_n$
- mainly, stable model semantics (beliefs)
- default reasoning on incomplete knowledge
(defaults + observation \rightsquigarrow conclusion)
- rules acts as constraints or derivation rules
(not as definitions)
- nonmonotonicity (addition of new info may contradict previous conclusions)
- No learning mechanisms are provided

Inductive Logic Programming (ILP)

- Given :
 - Background Knowledge \mathcal{B} and
 - Examples $E = E^+ \cup E^-$ ($\mathcal{B} \not\models E$)

Find a theory H such that

- $\mathcal{B} \cup H \models e$ for every $e \in E^+$
 - $\mathcal{B} \cup H \not\models f$ for every $f \in E^-$
- Present ILP uses Horn clauses for \mathcal{B} and H
 - less expressive language
 - monotonic reasoning
 - armed with various learning mechanisms
 - incremental learning (non-monotonic learning)
 - batch learning (monotonic learning)
 - top-down search and bottom-up search
 - inverse resolution
 - inverse entailment

Nonmonotonic Inductive Logic Programming (NMILP)

NMLP: expressive language, human commonsense reasoning, but no learning mechanisms

ILP: language with limited expressiveness, armed with learning mechanisms, but does not simulate human commonsense reasoning

NMILP: hopefully takes advantages of both paradigms

$$\text{NMILP} = \text{NMLP} + \text{ILP}$$

SLDNF Based Approaches

Representative Efforts

- Non-monotonic learning, M. Bain, S.Muggleton, 1992
- Learning Logic Programs with negation as failure, 1996
- Learning nonmonotonic logic program: learning exceptions, 1995
- Normal programs and multiple predicate learning, 1998
- Learning extended logic programs, 1997
- A three-valued framework for the induction of general programs, 1996

Incremental Learning

Initialize Σ to $\{\square\}$

repeat

 read the next (positive or negative) example

 while Σ is not correct w.r.t. the examples read so far

 if $\exists e^-$ s.t. $\Sigma \models e^-$

 specialize Σ by identifying a false clause
 and delete it from Σ

 if $\exists e^+$ s.t. $\Sigma \not\models e^+$

 generalize Σ by constructing a clause $C \models e$
 and add it to Σ

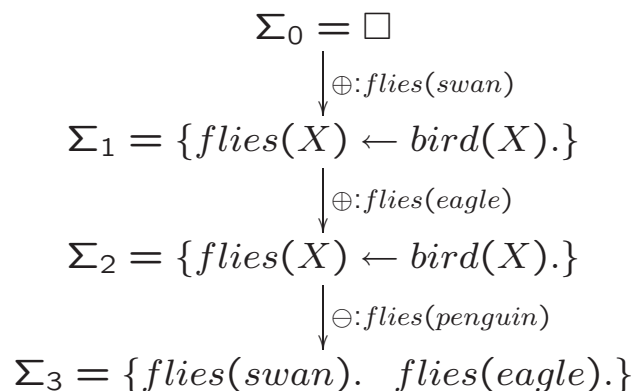
 until no examples left to read.

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An Example

$\mathcal{B} = \{bird(swan). \quad bird(eagle). \quad bird(penguin). \quad bird(pigeon).\}$

$E = \{\oplus flies(swan). \quad \oplus flies(eagle). \quad \ominus flies(penguin).\}$



An Example

$\mathcal{B} = \{bird(swan). \quad bird(eagle). \quad bird(penguin). \quad bird(pigeon).\}$

$E = \{\oplus flies(swan). \quad \oplus flies(eagle). \quad \ominus flies(penguin).\}$

$$\begin{array}{c} \Sigma_0 = \square \\ \downarrow \oplus: flies(swan) \\ \Sigma_1 = \{flies(X) \leftarrow bird(X).\} \\ \downarrow \oplus: flies(eagle) \\ \Sigma_2 = \{flies(X) \leftarrow bird(X).\} \\ \downarrow \ominus: flies(penguin) \\ \Sigma_3 = \{flies(swan). \quad flies(eagle).\} \end{array}$$



comments

1. monotonic reasoning (Horn clauses based)
2. non-monotonic learning (correct info not preserved, e.g., both Σ_1 and Σ_2 imply $flies(penguin)$, but Σ_3 does not.)
3. may result in poor learning quality
4. due to problem of “overly(drastic)-specialization”
5. we desire to preserve correct info
6. can not be achieved by any forms of “incremental-specialization” within classical logic framework
7. **SOLUTION: introducing negation !**

Closed World Specialization

Input:

set of clauses T (possibly with negation) and ground atom A s.t. $T \models A$ and A is incorrect

Operations:

Generate proof of $T \models A$ using SLDNF-resolution

Assume $C \in T$ resolved with $\leftarrow A$

Let $C = Hd : -Bd$

Let θ be the substitution for variables in C

If literal $notB \in Bd$

Let $T' = T \cup \{B\theta\}$

else

Let $\{V_1, \dots, V_n\}$ be the domain of θ

Let q be a predicate symbol not found in T

Let $B = q(V_1, \dots, V_n)$

Let $T' = T - \{C\} \cup \{Hd : -(Bd \cup notB)\} \cup \{B\theta\}$

Output: T'

Note: T' specializes T , but not in traditional sense, since T' has a new predicate symbol.

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In our example, the following theory will be learned

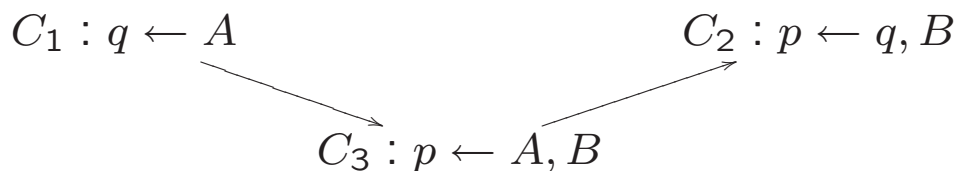
$\{flies(X) \leftarrow bird(X), not\ flightless(X). \ flightless(penguin).\}$

Now since $flightless(penguin)$ is true, $not\ flightless(penguin)$ is false. Therefore, the newly learned theory does not derive $flies(penguin)$ any more.

Moving from ILP to NMILP

Inverse Resolution is not directly applicable in NMILP !

Inverse resolution:(absorption)



- Σ_1 generalizes Σ_2 if $\Sigma_2 \models a$ implies $\Sigma_1 \models a$
- Denote $\Sigma = \{C_1, C_3\}$, $A(\Sigma) = \{C_1, C_2\}$.
- $A(\Sigma)$ generalizes Σ in Horn clausal logic

In NMLP, however

- $A(\Sigma)$ does not necessarily generalizes Σ
 $\Sigma = \{p \leftarrow \neg q, q \leftarrow r, s \leftarrow r, s \leftarrow\}$ (V:3,2,2)
 $A(\Sigma) = \{p \leftarrow \neg q, q \leftarrow s, s \leftarrow r, s \leftarrow\}$
 Then, $\Sigma \models p$ but $A(\Sigma) \not\models p$.
- It may be the case that Σ is consistent, but $A(\Sigma)$ is not.
 $\Sigma = \{p \leftarrow q, \neg p, q \leftarrow r, s \leftarrow r, s \leftarrow\}$ (V:3,2,2)
 $A(\Sigma) = \{p \leftarrow q, \neg q, q \leftarrow s, s \leftarrow r, s \leftarrow\}$
 Then, Σ is consistent, but $A(\Sigma)$ is not.
- ...

Inverse Entailment is not directly applicable to NMILP !

Deduction Theorem (Horn clausal logic)

For **any** formula A , we have

$$P \cup \{R\} \models A \iff P \models R \rightarrow A$$

Inverse entailment:

Given Horn program B and an example E , deduction theorem gives:

$$B \cup \{H\} \models E \iff B \models (H \rightarrow E) \quad (1)$$

$$\iff B \models (\neg E \rightarrow \neg H) \quad (2)$$

$$\iff B \cup \{\neg E\} \models \neg H \quad (3)$$

$B \cup \{\neg E\} \models \neg H$ serves as a necessary condition for constructing H .

In NMLP, however

- Deduction theorem in Eq. (1) and (3) does not hold in general
- Contrapositive implication in Eq. (2) is undefined

Stable Model Based Approaches

Main Results (by Chiaka Sakama)

Deduction Theorem (Horn clausal logic)

For **any** formula A , we have

$$P \cup \{R\} \models A \iff P \models R \rightarrow A$$

Entailment Theorem (NMLP)

For any **ground** literal A , we have

$$P \cup \{R\} \models_S A \implies P \models_S R \rightarrow A \quad (i)$$

$$P \cup \{R\} \models_S A \iff P \models_S R \rightarrow A \text{ and } P \models_S R \quad (ii)$$

Contrapositive rule in NMLP

$$R : A_0 \leftarrow A_1, \dots, A_m, \text{not } A_{m+1}, \dots, \text{not } A_n$$

$$R^c : \text{not } A_1; \dots, \text{not } A_m; \text{not not } A_{m+1}, \dots, \text{not not } A_n \leftarrow \text{not } A_0$$

$$R^c : \leftarrow A_1, \dots, A_m, \text{not } A_{m+1}, \dots, \text{not } A_n, \text{not } A_0$$

$$\text{We can prove that } P \models_S R \iff P \models_S R^c \quad (iii)$$

Inverse Entailment in NMLP

Given normal program B and a positive example E such that

$$B \models_S \text{not } E \quad (iv)$$

Then

$$B \cup \{H\} \models_S E \iff \text{by (i)} \quad B \models_S (H \rightarrow E)$$

$$\iff \text{by (iii)} \quad B \models_S (\text{not } E \rightarrow \text{not } H)$$

consider $H = p(x_1, \dots, x_k)$

where

p is a new atom

$$\implies \text{by (ii) and (iv)} \quad B \cup \{\text{not } E\} \models_S \text{not } H$$

So $B \cup \{\text{not } E\} \models_S \text{not } H$ serves as a necessary condition for H .

This necessary condition can be simplified as $B \models_S \text{not } H$.

Learning from a single positive example

Classical Inverse Entailment(IE):

- necessary condition for H : $B \wedge \neg E \models \neg H$ (*)
- let Bot be the conjunction of ground literals which are true in every model of $B \wedge \neg E$.
- we **consider** $Bot \models \neg H$ (but note: this IE is not complete since condition (*) does not imply $Bot \models \neg H$).
- $H_0 = \neg Bot$ is a trivial valid (ground) candidate of H .
- organize H_0 s.t. target predicate atom A is left to " \leftarrow ".
- generalizing H_0 by replacing constants with variables, we get a most specific hypothesis with variables.

NMLP Inverse Entailment(NMLP_IE):

- necessary condition for H : $B \models_S not H$ (**)
(same as $B \cup \{not E\} \models_S not H$)
- let $M^+ = M \cup \{not l \mid l \notin M \text{ and } l \in \mathcal{HB}\}$, where M is the stable model of B and \mathcal{HB} is the Herbrand model of B .
- condition (**) **implies** $M^+ \models not H$.
- let $\Gamma = \{K \in M^+ \mid K \text{ is relevant to } L \text{ and isinvolved in } B \cup \{E\}\}$.
- since $M^+ \models \Gamma$, we have $M^+ \models not r_0$ where $r_0 = \leftarrow \Gamma$.
- integrity constraint $r_0 = \leftarrow \Gamma$ is a trivial valid (ground) candidate of H .
- shift the target predicate atom to the left of " \leftarrow " in r_0 .
- generalizing r_0 by replacing constants with variables, we get a most specific hypothesis with variables.

Illustration

Given:

$B = \{bird(X) \leftarrow penguin(X). \quad bird(tweety). \quad penguin(polly).\}$

$E = \{\oplus flies(tweety).\}$

Note: $B \models not\ flies(tweety).$

Steps:

stable model of B (same as that of B not E):

$M = \{bird(tweety). \quad bird(polly). \quad penguin(polly).\}$

expansion of M :

$M^+ = \{bird(tweety). \quad bird(polly). \quad penguin(polly). \\ not\ penguin(tweety). \quad not\ flies(tweety). \quad not\ flies(polly).\}$

integrity constraint:

$r_0 = \leftarrow bird(tweety), not\ penguin(tweety), not\ flies(tweety).$

shift the atom with target predicate to the left side:

$r_0 = flies(tweety) \leftarrow bird(tweety), not\ penguin(tweety).$

generalize r_0 by replacing constant with variables:

$H = flies(X) \leftarrow bird(X), not\ penguin(X).$