Inductive Logic Programming Basic Approaches

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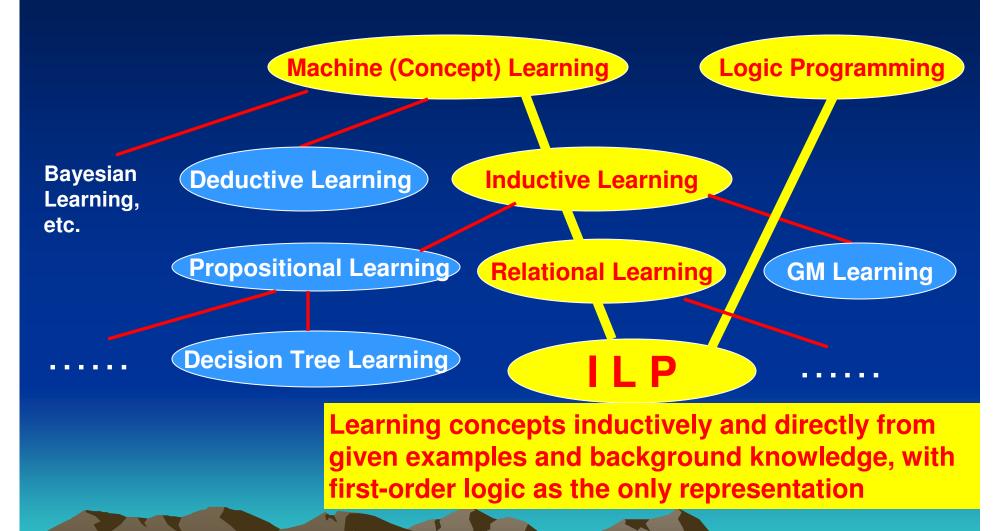
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Outlines

Introduction
 Basic Approaches
 A Simple Demo
 ILP In The Future

- ILP and Machine Learning
- Problem Specification
- An Simple Example
- Different ILP Learners
- ILP Search Space

ILP and Machine Learning (1)



Introduction: ILP and Machine Learning (2)

- is the intersection of inductive Machine Learning and Logic Programming
- inductively and directly learns concepts
- examples, background knowledge and target concepts are all represented in form of first-order logic
- more powerful than propositional learning (because)

ILP Problem Specification

Given

- training examples \mathcal{E} , $\mathcal{E} = \mathcal{E}^+ \cup \mathcal{E}^-$
- background knowledge $\mathcal{B}, \mathcal{B} \neq \mathcal{E}$

Find

target concepts *H*, which are complete, *B* ∪ *H* ⊨ *E*⁺, and consistent, *B* ∪ *H* ∪ *E*⁻ |≠ ∏ with respect to *B* and *E*

An Simple Example

Training Examples
 \$\mathcal{E}^+\$ = { daughter(mary, ann). daughter(eve, tom). }
 \$\mathcal{E}^-\$ = { daughter(tom, ann). daughter(eve, ann). }

Concept learned:

 Background Knowledge parent(ann, mary).
 parent(ann, tom).
 parent(tom, eve).
 parent(tom,bob).
 female(ann).
 female(mary).
 female(eve).

 $daughter(X,Y) \leftarrow female(X), parent(Y,X)$

Different ILP Learners

- Single concept learners and multiple concepts learners
- Batch learners and incremental learners
- Non-Interactive learners and interactive learners

Empirical ILP Learners: non-interactive single concept batch learners

ILP Search Space (1)

structure

- ILP problem is a search problem
- ILP search space consists of all syntactically legal hypotheses (clauses) constructed from the predicates provided by the background knowledge
- Very big search space

ILP Search Space (2)

An Example

If target concept : daughter(X,Y), background knowledge : femal(tom),..., parent(tom,bob)then the following hypotheses are in the search space: d(X,Y) $d(X,Y) \leftarrow f(X), p(X,Y)$ $d(X,Y) \leftarrow f(X)$ $d(X,Y) \leftarrow f(Y), p(X,Y)$ $d(X,Y) \leftarrow f(Y)$ $d(X,Y) \leftarrow f(X), p(Y,X)$ $d(X,Y) \leftarrow p(X,Y)$ $d(X,Y) \leftarrow f(Y), p(Y,X)$ $d(X,Y) \leftarrow p(Y,X)$ $d(X,Y) \leftarrow f(X), p(X,X)$ $d(X,Y) \leftarrow p(Y,X)$ $d(X,Y) \leftarrow f(Y), p(Y,Y)$ $d(X,Y) \leftarrow p(Y,Y)$ $d(X,Y) \leftarrow f(Y), p(Y,Y)$

ILP Search Space (4)

Generality relations

- More-general-than
- More-specific-than
- No-more-general-than
- No-more-specific-than
 (defined based on Θ-subsumption)

ILP Search Space (5)

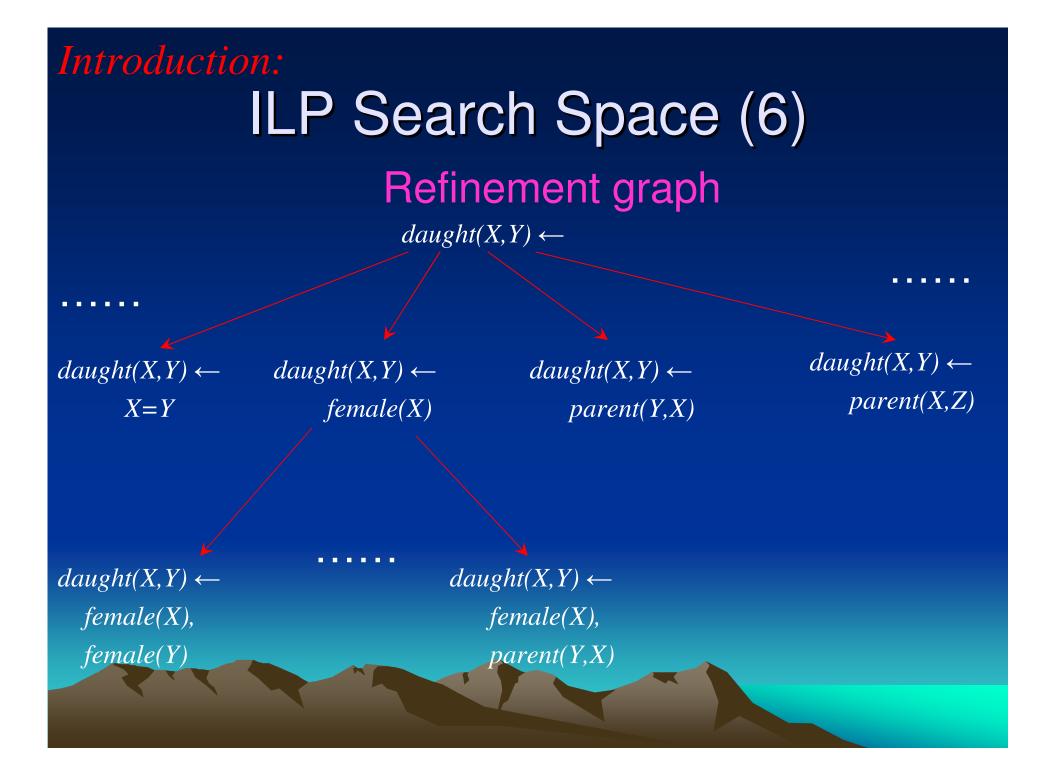
Operations

Specializations :

- Add literals into the clause body
- Apply substitutions to the clause

Generalizations :

- Remove literals from the clause body
- Apply inverse-substitutions to the clause



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Basic Approaches

- Top-down Approaches
- Bottom-up Approaches
- Hybrid Approaches
- Summary

Basic Approaches: Top-down Approaches (1)

Overview

- Use specialization
- Keep a refinement graph
- Search from the most general clause down to less general clauses, i.e., top-down,

(potentially adding literals into the clause body)

Basic Approaches: Top-down Approaches (2) <u>Generic Top-down Algorithm (for e.g. FOIL)</u> E' := E H := Ø specialization repeat c := T ←. repeat c := refinement(c)until some criterion is satisfied $H := H U \{c\}$ B := B U {c} E' := E' - { positive examples covered by B } until some criterion is satisfied

Basic Approaches: Bottom-up Approaches (1)

Two main techniques:

Relative Least General Generalization
 Inverse Resolution

(all use inverse substitution in different ways)

Basic Approaches: Bottom-up Approaches (2) Relative Least General Generalization (*rlgg*)

- *rlgg* is based on least general generalization *lgg*
- *lgg(structure1,structure2)* is defined between any two structures, e.g.,
 log(parent(ann marg)) parent(ann tom)) = parent(ann X
 - *lgg(parent(ann,mary), parent(ann,tom)) = parent(ann,X)*
- *rlgg* is *lgg* of two ground atoms *A1* and *A2* with respect to background knowledge *K*,
 rlgg(A1,A2) = lgg((A1←K),(A2←K))

Basic Approaches: Bottom-up Approaches (3) <u>rlgg based algorithms (for e.g. Golem)</u>

//assume background knowledge is a set of ground facts

E' := E H := Ø

Repeat

. Ер := Ø

c := a clause which covers no examples

repeat

Ep := randomly pick several pairs of examples from E' - Ep compute rlggs of the pairs using $rlgg(e1,e2) = lgg((e1 \leftarrow B),(e2 \leftarrow B))$ compute rlggs of the rlggs obtained above and c c := choose the rlgg with the greatest coverage Ep := Ep - { those examples covered by c } until no more positive examples are covered by c H := H U {c} B := B U {c} E' := E' - { positive examples covered by H and B} until some criterion is satisfied

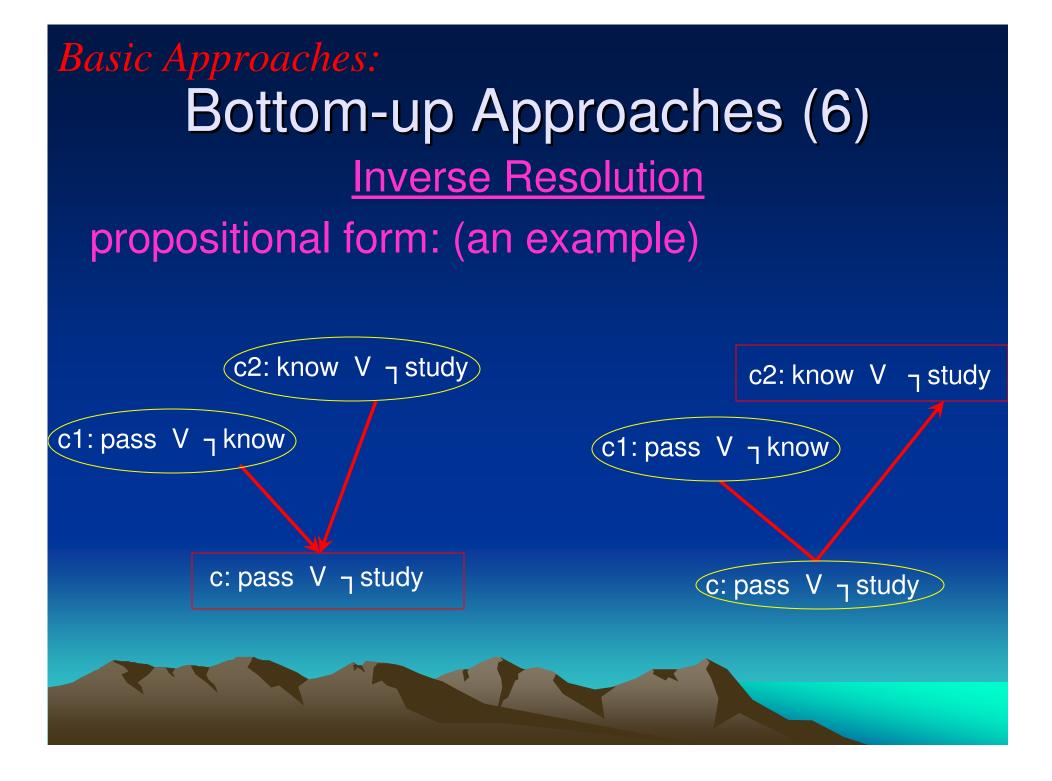
generalization

Basic Approaches: Bottom-up Approaches (4) Inverse Resolution

Resolution:

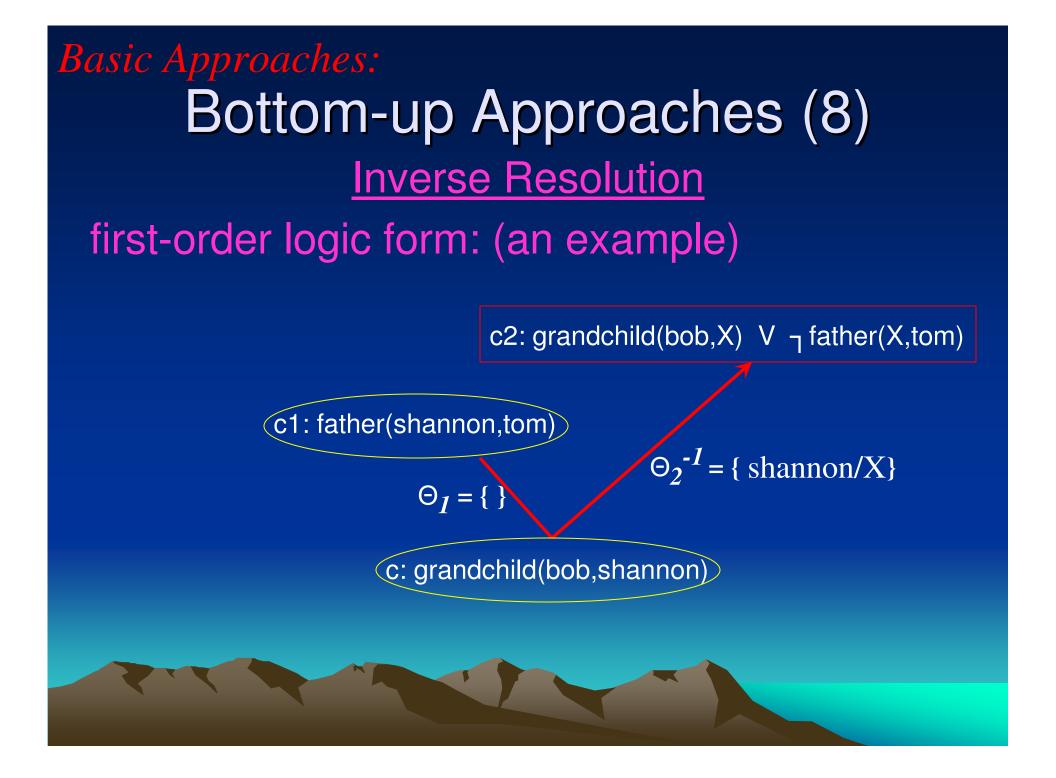
Given clause c1 and c2, derive resolvent c Inverse resolution: Given clause c1 and resolvent c, derive another clause c2 Two forms: propositional form first-order logic form Basic Approaches: Bottom-up Approaches (5) Inverse Resolution

propositional form: resolution (find L in c1 and $\neg L$ in c2) c1 ^ c2 \models c c = (c1- {L}) U (c2 - { $\neg L$ }) inverse resolution c2=(c-(c1-{L})) U { $\neg L$ }



Basic Approaches: Bottom-up Approaches (7) Inverse Resolution

first-order logic form: resolution (find L_1 in c1 and L_2 in c2 s.t. $L_1\Theta_1 = L_2\Theta_2$) c1 ^ c2 \models c c = (c1- { L_1 }) Θ_1 U (c2 - { L_2 }) Θ_2 inverse resolution c - (c1- { L_1 }) Θ_1 = (c2 - { L_2 }) Θ_2 $L_2 = L_1 \Theta_1 \Theta_2^{-1}$ c2 = (c - (c1-{ L_1 }) Θ_1) Θ_2^{-1} U { $\neg L_1 \Theta_1 \Theta_2^{-1}$ }



Basic Approaches: Bottom-up Approaches (9) Inverse resolution based algorithms (for e.g. Cigol)

E' := E H := Ø while E' ≠ Ø do e := the next positive example, invs := all the inverse resolutions of e and B c := choose the one with the highest accuracy H := H U {c} B := B U {c} E' := E' - { positive examples covered by B } Basic Approaches: Hybrid Approaches (1)

Use most specific boundary (Progol)

Use general and specific boundaries

Translate into propositional learning problem

Basic Approaches: Hybrid Approaches (2)

Use most specific boundary (Progol)

E' := E H := \oint while E' $\neq \oint$ do e := the next positive example \bot := the most specific clause from e and B c := top-down search a best clause between T \leftarrow . and \bot H := H U {c} B := B U {c} E' := E' - { positive examples covered by B } Basic Approaches: Hybrid Approaches (3)

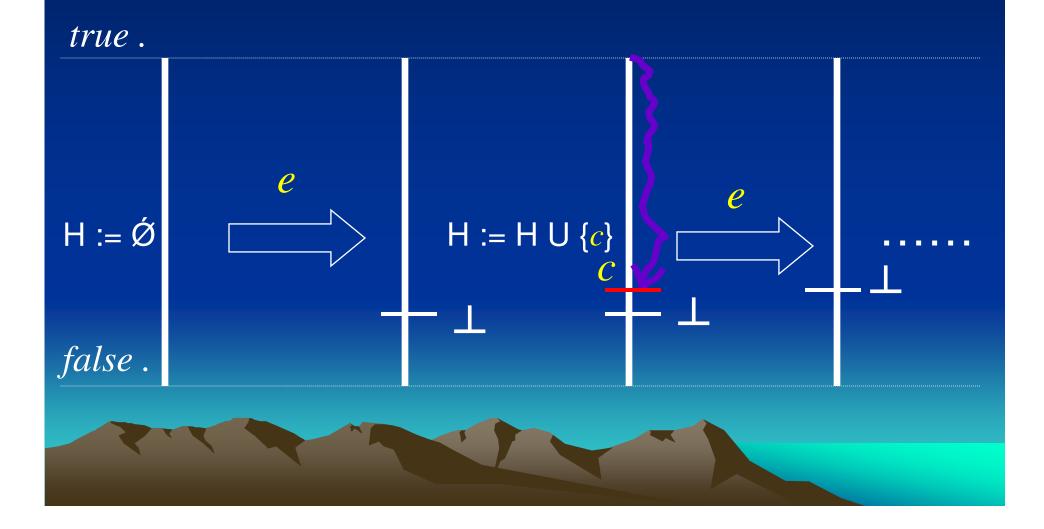
Use most specific boundary (Progol)

Consider examples one by one, using resolution, sounds *bottom-up*

Use resolution to construct a lower bound \perp from B and e, instead of a hypothesis directly

Then search from the very top down ¹ to find a clause which covers e and does not cover any of the negative examples, sounds *top-down*

Basic Approaches: Hybrid Approaches (4) Use most specific boundary (Progol)



Basic Approaches: Hybrid Approaches (5)

Maintain a upper bound and a lower bound

E' := E Bound_{lower} = true ← . Bound_{lower} = fase ← true . while E' ≠ Ø do e := the next positive example if e is positive Bound_{lower} = generalize(Bound_{lower}) which covers e but none of E⁻ if e is negative

Bound_{upper} = specialize(Bound_{upper}) which does not cover e

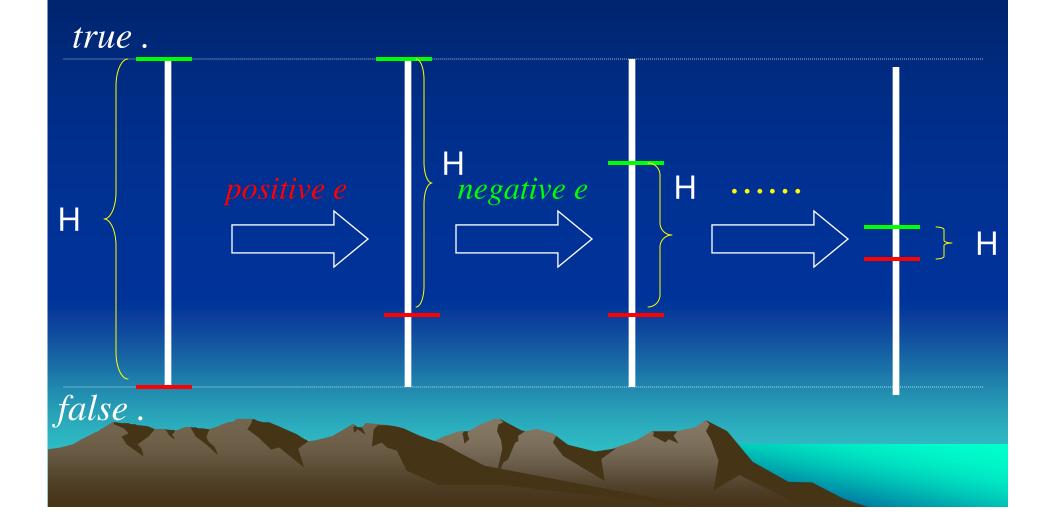
 $E' := E' - \{e\}$

H := { those hypotheses in between Bound_{upper} and Bound_{lower} }

Basic Approaches: Hybrid Approaches (6) Maintain a upper bound and a lower bound

 Positive examples raise the lower bound up
 Negative examples push the upper bound down

Basic Approaches: Hybrid Approaches (7) Use upper and lower boundaries



Basic Approaches:

Summary

Top-down approaches:

perform specialization operations

search the refinement graph top-down in brute-force, unique starting point successor hypotheses generated based only on the syntax of the current hypothesis representation, independent of the coming data generate-and-test fashion the impact of noisy data is minimized batch mode: all examples are considered simultaneously

Bottom-up approaches:

perform generalization operations search is guided bottom-up by inverse resolution, multiple starting points hypotheses generated based on analysis of an individual example example-driven fashion more easily misled by noisy data incremental mode: examples are considered one at a time

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Sample Problem

Target concept: daughter(X, Y)**Background Knowledge:**

parent(ann,mary). *parent(ann,tom). female(mary).* parent(tom,eve). parent(tom,ian). **Examples:**

female(ann). female(eve).

% Positive examples daughter(mary,ann). daughter(tom,ann). daughter(eve,tom).

% Negative examples daughter(eve,ann).

Progol Output (1)

CProgol Version 4.4 [Testing for contradictions] [No contradictions found]

[Generalising daughter(mary,ann).] [Most specific clause is]

daughter(A,B) :- parent(B,A), female(A), female(B).

Progol Output (2)

[Learning daughter/2 from positive examples] [C:-9993,8,10000,0 daughter(A,B).] [C:-9994,8,10000,0 daughter(A,B) :- parent(B,A).] [C:-9994,8,10000,0 daughter(A,B) :- female(A).] [C:-19996,4,10000,0 daughter(A,B) :- female(B).] [C:3,8,2,0 daughter(A,B) :- parent(B,A), female(A).] [C:-19998,4,10000,0 daughter(A,B) :- parent(B,A), female(B).] [C:-19998,4,10000,0 daughter(A,B) :- female(A), female(B).] [C:-19998,4,10000,0 daughter(A,B) :- female(A), female(B).] [7 explored search nodes] f=3,p=8,n=2,h=0

Progol Output (3)

[Result of search is]

daughter(A,B) :- parent(B,A), female(A).

[2 redundant clauses retracted]

daughter(A,B) :- parent(B,A), female(A).

[Total number of clauses = 1]

[Time taken 0.00s]

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ILP In The Future

- Novel search methods
- Incorporation of explicit probabilities
- Special-purpose reasoners
- Parallel implementations (PILP)
- Enhanced human interaction

(handle huge data sets in the future)

Thank You!